

## Refine Search

### Search Results -

Terms	Documents
L10 and color near\$4 chang4	0

Database:

US Pre-Grant Publication Full-Text Database  
 US Patents Full-Text Database  
 US OCR Full-Text Database  
 EPO Abstracts Database  
 JPO Abstracts Database  
 Derwent World Patents Index  
 IBM Technical Disclosure Bulletins

Search:

L26



Refine Search

Recall Text



Clear

Interrupt

### Search History

DATE: Friday, February 17, 2006   [Printable Copy](#)   [Create Case](#)

<u>Set</u> <u>Name</u>	<u>Query</u>	<u>Hit</u> <u>Count</u>	<u>Set</u> <u>Name</u> result set
<i>DB=PGPB,USPT; PLUR=YES; OP=OR</i>			
<u>L26</u>	l10 and color near\$4 chang4	0	<u>L26</u>
<u>L25</u>	l16 and color near chang\$4 same (airflow or HVAc or cooler or heater or environment\$4 or humidity)	0	<u>L25</u>
<u>L24</u>	l10 and color near4 chang4	0	<u>L24</u>
<u>L23</u>	l15 and color near4 chang4	0	<u>L23</u>
<u>L22</u>	l16 and color near4 chang4	0	<u>L22</u>
<u>L21</u>	l16 and color near chang4	0	<u>L21</u>
<u>L20</u>	l16 and color near chang4 same (airflow or HVAc or cooler or heater or environment\$4 or humidity)	0	<u>L20</u>
<u>L19</u>	20040256474	1	<u>L19</u>
<u>L18</u>	2004025647	0	<u>L18</u>
<u>L17</u>	l16 not l14	15	<u>L17</u>
<u>L16</u>	L15 and (imag\$4 or camera or scan\$4)	18	<u>L16</u>

<u>L15</u>	(robot\$4 or mobil\$4 ) and (airflow or HVAc or cooler or heater or environment\$4 or humidity)and (indicat\$4 or sensor or detector) and 236 \$.ccls.	89	<u>L15</u>
<u>L14</u>	(robot\$4 or mobil\$4 ) same (airflow or HVAc or cooler or heater or envvironment\$4 or humidity)same (indicat\$4 or sensor or detector) and 236 \$.ccls.	19	<u>L14</u>
<u>L13</u>	(robot\$4 or mobil\$4 ) same (airflow or HVAc or cooler or heater )same (indicat\$4 or sensor or detector)	452	<u>L13</u>
<u>L12</u>	(robot\$4 or mobil\$4 ) same (airflow or HVAc or cooler or heater )near (indicat\$4 or sensor or detector)	37	<u>L12</u>
<u>L11</u>	(robot\$4 or mobil\$4 or trav\$4) same (airflow or HVAc or cooler or heater ) near (indicat\$4 or sensor or detector)	160	<u>L11</u>
<u>L10</u>	(robot\$4 or mov\$6 or mobil\$4 or trav\$4) same (airflow or temperature )near (indicat\$4 or sensor or detector)	11831	<u>L10</u>
<u>L9</u>	(robot\$4 or mov\$6 or mobil\$4 or trav\$4) same (fan or air near condition or airflow or temperature)	283297	<u>L9</u>
<u>L8</u>	6283380.pn. and direction	1	<u>L8</u>
<u>L7</u>	20010020291 and direction	4	<u>L7</u>
<u>L6</u>	6283380.pn. and magnitude	0	<u>L6</u>
<u>L5</u>	20010020291 and translat\$6	32	<u>L5</u>
<u>L4</u>	20010020291 and sequence\$4	32	<u>L4</u>
<u>L3</u>	((design\$4 and program\$4 and (information or document\$4 or database or data) near4 (stor\$4 or memory) and program near4 automation ) and execut\$4 and logic) and 20010020291	7	<u>L3</u>
<u>L2</u>	((design\$4 and program\$4 and (information or document\$4 or database or data) near4 (stor\$4 or memory) and program near4 automation ) and execut\$4 and logic) and 2001002029	0	<u>L2</u>
<u>L1</u>	((design\$4 and program\$4 and (information or document\$4 or database or data) near4 (stor\$4 or memory) and program near4 automation ) and execut\$4 and logic)	411	<u>L1</u>

END OF SEARCH HISTORY